#### Machine Learning and Pervasive Computing

Stephan Sigg

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#### Overview and Structure

- 13.04.2015 Organisation
- 13.04.2015 Introduction
- 20.04.2015 Rule-based learning
- 27.04.2015 Decision Trees
- 04.05.2015 A simple Supervised learning algorithm
- 11.05.2015 -
- **18.05.2015** Excursion: Avoiding local optima with random search 25.05.2015 –
- 01.06.2015 High dimensional data
- 08.06.2015 Artificial Neural Networks
- 15.06.2015 k-Nearest Neighbour methods
- 22.06.2015 Probabilistic graphical models
- 29.06.2015 Topic models
- 06.07.2015 Unsupervised learning
- 13.07.2015 Anomaly detection, Online learning, Recom. systems

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#### Outline

Unsupervised learning

#### Self Organizing Maps

Introduction Definition Example







### Unsupervised learning



Supervised:  $\{(x_{1,1}, x_{1,2}) \rightarrow y_1, (x_{2,1}, x_{2,2}) \rightarrow y_2, \dots, (x_{n,1}, x_{n,2}) \rightarrow y_n\}$ Unsupervised:  $\{(x_{1,1}, x_{1,2}), (x_{2,1}, x_{2,2}), \dots, (x_{n,1}, x_{n,2})\}$ 

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#### Unsupervised learning



Supervised:  $\{(x_{1,1}, x_{1,2}) \rightarrow y_1, (x_{2,1}, x_{2,2}) \rightarrow y_2, \dots, (x_{n,1}, x_{n,2}) \rightarrow y_n\}$ Unsupervised:  $\{(x_{1,1}, x_{1,2}), (x_{2,1}, x_{2,2}), \dots, (x_{n,1}, x_{n,2})\}$ 



#### Unsupervised learning

#### k-means algorithm

#### Iteratively find k clusters in the data

#### Init Randomly choose k points as initial cluster centroids Repeat :

- $\rightarrow~$  Assign samples to these cluster centroids conditioned on distance
- $\rightarrow\,$  Move cluster centroids to the center weight of the points associated to them



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#### Unsupervised learning

k-means algorithm





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#### Unsupervised learning

k-means algorithm

Init: k cluster centroids  $\mu_i$ chosen randomly





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# Self Organizing Maps

### Unsupervised learning

k-means algorithm

Init: k cluster centroids  $\mu_i$  chosen randomly

Repeat:

1: assign samples to centroids conditioned on distance



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# Self Organizing Maps

# Unsupervised learning

k-means algorithm

Init: k cluster centroids  $\mu_i$  chosen randomly

Repeat:

1: assign samples to centroids conditioned on distance

2: 
$$\mu_j(t+1) = \frac{1}{C_j} \sum_{i=1}^{C_j} x^{(i)}$$



(a)

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# Self Organizing Maps

# Unsupervised learning

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# Self Organizing Mass

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### Unsupervised learning

k-means algorithm

#### How to randomly initialise the k-means algorithm

The k-means algorithms may compute different solutions for different initial choice of cluster centroids

With respect to the overall distance of the samples to their cluster centroids, k-means might run into local optima



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### Unsupervised learning

k-means algorithm

#### How to randomly initialise the k-means algorithm

The k-means algorithms may compute different solutions for different initial choice of cluster centroids

With respect to the overall distance of the samples to their cluster centroids, k-means might run into local optima

#### Common choice of the initial k cluster centroids

Choose the initial k cluster centroids randomly from the set of training samples



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# Unsupervised learning

k-means algorithm







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### Unsupervised learning

k-means algorithm





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### Unsupervised learning

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## Unsupervised learning

k-means algorithm







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### Unsupervised learning

k-means algorithm







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### Unsupervised learning

k-means algorithm





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#### Unsupervised learning

k-means algorithm





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Unsupervised learning

#### Self Organizing Maps

Introduction Definition Example



## Introduction to self organising maps (SOM)

Proposed by Teuvo Kohonen<sup>1</sup>

input vec

- $\rightarrow\,$  Model of the self-organisation of neural connections
- $\rightarrow\,$  Maps high dimensional input to low dimensional (e.g. 2D) output





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#### Introduction to self organising maps (SOM) Relation to Neural Networks

#### Similarity

• Weighted inputs mapped to vector of outputs

#### Difference

- Considers neighbourhood relation and ordering of output layer
- Unsupervised
- Alternative learning and updating

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#### Introduction to self organising maps



Represent all points in a source space by points in a target space space by points in a target space.

Given a sequence of points in a sample space,

Create a mapping of these points into a target space that respects the neighbourhood relation in the sample space





# Introduction to self organising maps



SOM is a topology preserving lattice of predefined number of nodes Represents topology of elements in input space.

Algorithm inherits self-organisation property

- Able to produce organisation starting from total disorder.
- Defines and preserves neighbourhood structure between nodes

Learning by two layer neural network

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# Introduction to self organising maps



When a pattern  $\vec{\phi_i}$  is presented, each node (represented by outer neurons) in the target space computes its activation  $\vec{\phi_i} \cdot \vec{w}$ .

Most activated node  $y^*$  and weights to its neighbours are updated according to a learning rate  $\rho(t)$ 

$$w_{ki}(t+1) = w_{ki}(t) + \rho(t)\Lambda(|y-y^*|)(\overrightarrow{\phi_i} - w_{ki}(t))$$

 $\Lambda(\cdot)$  defines a non-increasing neighbourhood function and  $|y - y^*|$  describes the distance of nodes in the neighbourhood



#### SOM – Self organisation



#### SOM – Definition



Condensed definition of SOM from Cottrell et al.<sup>2</sup>

#### Self organising maps

- Let  $I = \{\overrightarrow{\eta_1}, \dots, \overrightarrow{\eta_{|S|}}\}$  be a set of *km*-dimensional vectors that are associated with nodes in a lattice.
- Neighbourhood structure provided by symmetrical neighbourhood function  $d: I \times I \to \mathbb{R}$  which depends on the distance between two nodes  $\overline{\eta_i}$  and  $\overline{\eta_i} \in I$ .
- State of the map at time t given by

$$\eta(t) = \left(\overrightarrow{\eta_1(t)}, \overrightarrow{\eta_2(t)}, \dots, \overrightarrow{\eta_{|S|}(t)}\right)$$

<sup>2</sup>M. Cottrell, J.C. Fort and G. Pages, *Theoretical aspects of the SOM algorithm*, Neurocomputing, pp. 119-138, vol 21, 1998.



#### SOM – Definition



#### Self organising map algorithm

The SOM algorithm is recursively defined by

$$\begin{split} i_c \left( \overrightarrow{v(t+1)}, \overrightarrow{\eta(t)} \right) &= \arg \min \left\{ \left\| \overrightarrow{v(t+1)} - \overrightarrow{\eta_i(t)} \right\|, \overrightarrow{\eta_i(t)} \in \eta(t) \right\}, \\ \overrightarrow{\eta_i(t+1)} &= \overrightarrow{\eta_i(t)} - \varepsilon_t d \left[ i_c \left( \overrightarrow{v(t+1)}, \overrightarrow{\eta(t)} \right), \overrightarrow{\eta_i} \right] \\ &\cdot \left( \overrightarrow{\eta_i(t)} - \overrightarrow{v(t+1)} \right), \forall \overrightarrow{\eta_i} \in I. \end{split}$$

In this formula,  $i_c\left(\overrightarrow{v(t+1)}, \overrightarrow{\eta(t)}\right)$  corresponds to the node in the network that is closest to the input vector.

Parameter  $\varepsilon_t$  controls the adaptability.

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#### SOM – Operational principle



Input values  $v_i(t)$  are to be mapped onto the target space



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### SOM – Operational principle



Node with the lowest distance is associated with the input value:

$$i_{c}\left(\overrightarrow{v(t+1)},\overrightarrow{\eta(t)}
ight) = \operatorname{argmin}\left\{\left\|\overrightarrow{v(t+1)} - \overrightarrow{\eta_{i}(t)}\right\|,\overrightarrow{\eta_{i}(t)} \in \eta(t)
ight\}$$

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### SOM – Operational principle



Nodes in the neighbourhood of the associated node are moved closer to the input value



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### SOM – Operational principle



Nodes in the neighbourhood of the associated node are moved to the input value

$$\overrightarrow{\eta_i(t+1)} = \overrightarrow{\eta_i(t)} - \varepsilon_t d \left[ i_c \left( \overrightarrow{v(t+1)}, \overrightarrow{\eta(t)} \right), \overrightarrow{\eta_i} \right] \\ \cdot \left( \overrightarrow{\eta_i(t)} - \overrightarrow{v(t+1)} \right), \forall \overrightarrow{\eta_i} \in I.$$

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## SOM – Example application: TEA





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#### SOM – Example application: TEA





SOM – Remarks

# Self Organizing Maps)

SOM algorithm always converges<sup>3</sup>

Normalisation of input vectors might improve numerical accuracy

Not guaranteed that self-optimisation will always occur (Dependent on choice of parameters)

Difficult to set parameters of the model since SOM is not optimising any well-defined function<sup>4</sup>

If neighbourhood is chosen to be too small, the map will not be ordered globally

<sup>&</sup>lt;sup>4</sup>E. Erwin, K. Obermayer, K. Schulten: Self-organising maps: Ordering, convergence properties and energy functions. Biological Cybernetics, 67, 47-55, 1992



<sup>&</sup>lt;sup>3</sup>Y. Cheng, Neural Computation, 9(8), 1997.



#### Problems of SOMs



Map created as target space might have several orientations

One part of the map might follow one orientation, while other parts are following other orientations



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(Self Organizing Maps)

# **Questions?**

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#### Literature

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- R.O. Duda, P.E. Hart, D.G. Stork: Pattern Classification, Wiley, 2001.





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